

## Vector Identities

1.  $\nabla(f + g) = \nabla f + \nabla g$
2.  $\nabla(cf) = c\nabla f$ , for a constant  $c$
3.  $\nabla(fg) = f\nabla g + g\nabla f$
4.  $\nabla(f/g) = (g\nabla f - f\nabla g)/g^2$ , at points where  $g(\mathbf{x}) \neq 0$
5.  $\nabla \cdot (\mathbf{F} + \mathbf{G}) = \nabla \cdot \mathbf{F} + \nabla \cdot \mathbf{G}$
6.  $\nabla \times (\mathbf{F} + \mathbf{G}) = \nabla \times \mathbf{F} + \nabla \times \mathbf{G}$
7.  $\nabla(\mathbf{F} \cdot \mathbf{G}) = (\mathbf{F} \cdot \nabla)\mathbf{G} + (\mathbf{G} \cdot \nabla)\mathbf{F} + \mathbf{F} \times (\nabla \times \mathbf{G}) + \mathbf{G} \times (\nabla \times \mathbf{F})$
8.  $\nabla \cdot (f\mathbf{F}) = f\nabla \cdot \mathbf{F} + \mathbf{F} \cdot \nabla f$
9.  $\nabla \cdot (\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot (\nabla \times \mathbf{F}) - \mathbf{F} \cdot (\nabla \times \mathbf{G})$
10.  $\nabla \cdot (\nabla \times \mathbf{F}) = 0$
11.  $\nabla \times (f\mathbf{F}) = f\nabla \times \mathbf{F} + \nabla f \times \mathbf{F}$
12.  $\nabla \times (\mathbf{F} \times \mathbf{G}) = (\nabla \cdot \mathbf{G})\mathbf{F} - (\nabla \cdot \mathbf{F})\mathbf{G} + (\mathbf{G} \cdot \nabla)\mathbf{F} - (\mathbf{F} \cdot \nabla)\mathbf{G}$
13.  $\nabla \times (\nabla \times \mathbf{F}) = \nabla(\nabla \cdot \mathbf{F}) - \nabla^2 \mathbf{F}$
14.  $\nabla \times \nabla f = \mathbf{0}$
15.  $\nabla(\mathbf{F} \cdot \mathbf{F}) = 2(\mathbf{F} \cdot \nabla)\mathbf{F} + 2\mathbf{F} \times (\nabla \times \mathbf{F})$
16.  $\nabla^2(fg) = f\nabla^2 g + g\nabla^2 f + 2(\nabla f \cdot \nabla g)$
17.  $\nabla \cdot (\nabla f \times \nabla g) = 0$
18.  $\nabla \cdot (f\nabla g - g\nabla f) = f\nabla^2 g - g\nabla^2 f$
19.  $\mathbf{H} \cdot (\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot (\mathbf{H} \times \mathbf{F}) = \mathbf{F} \cdot (\mathbf{G} \times \mathbf{H})$
20.  $\mathbf{H} \cdot ((\mathbf{F} \times \nabla) \times \mathbf{G}) = ((\mathbf{H} \cdot \nabla)\mathbf{G}) \cdot \mathbf{F} - (\mathbf{H} \cdot \mathbf{F})(\nabla \cdot \mathbf{G})$
21.  $\mathbf{F} \times (\mathbf{G} \times \mathbf{H}) = (\mathbf{F} \cdot \mathbf{H})\mathbf{G} - (\mathbf{F} \cdot \mathbf{G})\mathbf{H}$
22.  $\nabla^2 f \equiv \nabla \cdot \nabla f$

Notes:

- $f$  and  $g$  denote scalar fields;  $\mathbf{F}$ ,  $\mathbf{G}$ , and  $\mathbf{H}$  denote vector fields.
- In Cartesian coordinates, the **vector Laplacian** is defined as  $\nabla^2 \mathbf{F} = \nabla^2 F_1 \hat{\mathbf{i}} + \nabla^2 F_2 \hat{\mathbf{j}} + \nabla^2 F_3 \hat{\mathbf{k}}$ , where  $\mathbf{F} = F_1 \hat{\mathbf{i}} + F_2 \hat{\mathbf{j}} + F_3 \hat{\mathbf{k}}$ . To generalize to other coordinate systems, the vector Laplacian is often considered to be defined by the relationship shown in identity #13 above.
- In Cartesian coordinates, the expression  $\mathbf{V} = (\mathbf{F} \cdot \nabla)\mathbf{G}$  has, by definition, the components  $V_i = \mathbf{F} \cdot (\nabla G_i)$  where  $\mathbf{G} = G_1 \hat{\mathbf{i}} + G_2 \hat{\mathbf{j}} + G_3 \hat{\mathbf{k}}$ . In other coordinate systems, the dependence of the unit vectors on position must be accounted for. (There's a good description of this in the 2nd appendix of *An Introduction to Fluid Dynamics* by G. K. Batchelor, Cambridge University Press, 1967.)
- In the expression  $\mathbf{U} = (\mathbf{F} \times \nabla) \times \mathbf{G}$ , the  $\nabla$  is to operate only on  $\mathbf{G}$ . In Cartesian coordinates,  $\mathbf{U}$  has components  $U_i = \mathbf{F} \times (\nabla G_i)$ .